



DEMO design and Diagnostics : a short summary of studies in EU

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### Outline



	Aims :
<ol> <li>Short Introduction on present status of tokamak plasma scenarios</li> </ol>	Where we are in the plasma scenarios
<ul> <li>2. DEMO design principles(tokamak fusion energy demonstrator) :</li> <li>MODELS for DEMO steady state and pulsed devices,</li> <li>physics analysis</li> <li>pros and cons</li> </ul>	EU FUSION ENERGY ROAD MAP Key points on the design Of DEMO, motivations for a Pulsed DEMO
<ul> <li>3.DEMO diagnostics and controls :</li> <li>principles of fusion reactor control and sensors (diagnostics)</li> <li>Minimum set of diagnostics for DEMO (pulsed and steady state)</li> <li>Necessary diagnostics for machine protection and burn control</li> <li>R&amp;D needed</li> <li>4.Conclusions</li> </ul>	The diagnostics are sensors For DEMO controls NO PHYSICS STUDIES ON DEMO Few systems only for BURN CONTROL and Machine protection KEY POINT : The resistence to neutron fluence ( total neutron flux integrated in time)



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### Scheme of a tokamak



In a plasma contaned in a toroidal device with axial magnetic field a current is induced by a transformer

PER LE NUOVE TECNOLOGIE, L'ENERGIA E LO SVILUPPO ECONOMICO SOSTENIBILE

A magnetic field results with elical field lines which close after a certain number of turns on surfaces called 'rationale surfaces'

Bpol~ Btoroidal/10;

Safety factor q=(number of toroidal turns /n poloidal turns)

 $=\frac{5a^2B}{RI}(1+k^2/2)$ 

magnetic shear S = (q/r) (dq/dr)

### Physics of confinement



Regimes of plasma confinement are classified in relation to the spatial scales relevant :

- i) Regimes where the relevant spatial scale is the plasma dimension are named L-mode (low confinement modes)
- ii) Regimes where the Larmor radius is the fundamental relevant scale are named H-modes (High Confinement)

#### the transition to H-mode is linked to a threshold

**power**  $P_{L-H} \sim C B_T n^{0.75} R^2$ .

For example in JET  $P_{L-H} \sim 8MW$ 

confinement scaling laws



Kadomtsev(1975) e Connor e Taylor(1977) demostrated

$$\omega_c \tau_E \propto B \tau_E \propto f(\rho^*, \beta, \nu^*, q, ...)$$

fit of data of confinament multi machine database

$$\omega_{ce} \tau_E \propto \rho^{*-2.7} \beta^{-0.9} v^{*-0.01} (scaling IPB98(y,2))$$

Recent Experiments on JET(EU) e DIIID(Ga, USA) dimonstrated that in the range of parameters useful for a demonstrative reactor

$$\omega_{ce} \tau_E \propto \rho^{*-3.0\pm0.3} \beta^{0.0} v^{*-0.3}$$

(D McDonalds and J Cordey Conf IAEA 2004,

McDonalds IAEA 2006, Valovic Nuclear Fusion 2006)

### © Evertsional regimes in a tokamak:corresponden ce of ENEN current profiles ↔ pressure profiles



EUROfusion Example of a discharge in ELMy H-mode



ELMs (edge localized modes) corrispond to instabilities generated when locally the beta limit is reached





Advanced Scenarios :current profiles and formation of

#### internal transport barriers

- Improved LHCD coupling leads to strong magnetic shear reversal during preheat
- strong internal transport barriers
- virtually no power threshold when compared to Optimised Shear





# Internal Transport Barriers



Profiles of density and ion temperature in JET record discharge in the FIRST Deuterium Tritium campaigns.

T F OISILL

### Power from fusion in magnetic confinement

$$P_{fusion} = 1/4 n_{ion}^2 < \sigma v > E_{fusion} \sim (nT)^2$$

- $P_{fusion} = 1.08 \ \beta^2 \ B^4. \ MW/m^3.$ 
  - $\beta$ =2 nT / (B<sup>2</sup>/2µ<sub>0</sub>) = [kinetic total pressure(ions+elettrons)] / magnetic pressure
- For example.  $(B^2/2\mu_0) = 10000$  pascal @ B=0.5T

Typical value of beta  $\beta$ ~1-10%

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#### Comments on Pfus vs (limits of) beta



#### $P_{\text{fusion}} = 1.08 \ \beta^2 \ B^4. \ MW/m^3.$ D+T $\rightarrow \alpha(3.5 \text{MeV}) + n(14.1 \text{MeV})$

 $Q_{fusion gain} = \frac{fusion power}{heating power}$ at the steady state  $\Rightarrow P_{heat} + P_{alpha} = \frac{3nT_e}{\tau_E}$  $\tau_{F} = energy confinement$  time  $Q = \frac{Pfus}{\frac{3nT_e}{\tau_E} - \frac{Pfus}{5}} = \frac{\overline{Q}}{1 - (\overline{Q}/5)}$  $\overline{Q} = \frac{Pfus}{Ploss} = \frac{4\beta^2 B^4 \tau_E}{3}$ 

 $\beta$  limited by MHD stability

$$\overline{Q} = \frac{P_{fus}}{P_{loss}} = \frac{4\beta^2 B^4 \tau_E}{3}$$

τE limited by the turbulent transport



Gain Q versus geometry and plasma parameters Scaling  $\tau_E(s) = 0.0562 * I^{0.93} * B^{0.15} * \left(\frac{a}{R}\right)^{0.58} * R^{1.97} * n^{0.41} * P^{-0.69} * M^{0.19} * k_a^{0.78}$ of confinem  $\beta = \beta_N \frac{I}{\alpha R}; \ \beta_N \le 0.035$  Beta limit ent time  $\overline{Q} = \frac{4}{3}\beta B^2 \tau_E = \frac{4}{3} * 0.0562 * \beta_N * I^{1.93} B^{1.15} * (\frac{R}{a})^{1.39} * a^{0.97} * n^{0.41} * P^{-0.69} * M^{0.19} * k_a^{0.78}$  $nGR = \frac{I}{\pi a^2}$  Density limit  $\overline{Q} \le 0.04686 * \beta_N * I^{2.34} * B^{1.15} * \left[\frac{R}{a}\right]^{1.39} * a^{-1.03} * P_{loss}^{-0.69} * M^{0.19} * k_a^{0.78}$ 

The gain factor depends upon :

•Geometry (a(minor radius) and aspect ratio R/a)

•Plasma current I,

magnetic field B

•beta  $\beta_N$ .

At a fixed geometry (R/a), magnetic field B and heating power P an increase of  $\beta_N$  and I of 10%  $\rightarrow$  **33%.** increase of Q





### DEMO DESIGN : STEADY STATE AND PULSED MODELS





#### Basic idea of steady state reactor

The idea of working at high  $\beta_N$  allows for a device with lower current and dimensions since Pfus<sup>( $\beta_N$ ) <sup>2</sup> \* Ip<sup>2</sup>.\*Bt<sup>2</sup>.R\*k</sup>

Minimizes the heating and current drive needs, since it allows higher values of beta poloidal and self-generated plasma current (bootstrap current).

In fact the fraction of bootstrap current scales as

(A=R/a=aspect ratio,  $\beta$ p=beta poloidal, Ib=bootstrap current, Ip=total plasma current :



The remaining part of the current must be supplied by Current Drive systems

The produced electric energy must be partly used for the Current Drive system: this part is A critical requirement for a SS reactor.

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### Analysis of SS DEMO MODELS



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### **EXAMPLES OF SS MODELS**



	ARIES RS	PPCS C	SLIM CS	ITER SS
R(m)	5,5	7,5	5,5	6,2
a(m)	1,375	2,5	2,1	2
Aspect ratio R/a	4	3	2,6	3,1
B(T) on axis	8	6	6	5,3
I(MA)	11,3	20	16,7	9
βN	4,8	4	4,3	2,9
fB	0,88	0,63	0,75	0,46
n/nG	1	1,5	1	0,78
HH(IPBy2)	1,15	1,3	1,3	1,6
Q	27	30	29,5	5
k elongation	1,9	1,9	2	1,8
δtriangularity	0,5	0,47	0,35	0,4
Fusion Power(GW)	2,17	3,41	2,95	0,36
Heating				
Power(MW)	80	112	100	70



**EU PPCS Models** 

#### O EUROfusion Analysis of DEMO scenarios (PPCS C, SS

for realistic Current Drive values ( $\gamma$ CD $\approx$ 0.3-0.4 10<sup>20</sup> A W<sup>-1</sup> 10<sup>20</sup> m<sup>-2</sup>) high bootstrap fraction is required fB $\geq$ 0.7-0.8 compatible with the power available of 110MW.

In the PPCS papers a more optimistic  $\gamma$ CD $\approx$ 0.7 10<sup>20</sup> A W<sup>-1</sup> 10<sup>20</sup> m<sup>-2</sup>, is assumed  $\gamma_{CD}$  (A W<sup>-1</sup> 10<sup>20</sup> m<sup>-2</sup>)

Analysis of DEMO scenarios (J Garcia et al 2008)



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#### Physics critical issues of SS DEMO



ITER steady state scenario assumes parameters (HHIPBy2=1.61, βN=2.93,fB=0.46, n/nG=0,78) never demonstrated in <u>integrated</u> <u>way</u> in present devices. Clearly for SLIM CS the same notation can be applied even more.



Y Sakamoto et al 2010

#### EUROfusion Achieved performances on DIIID and JT-60U in transient conditions





Integrated performances achieved in transient conditions . Comparison Of design values of SlimCS (red contour) and a) DIII-D discharge (#122004) and b) JT-60U discharge (#48246)



### DIIID /JT-60U discharges details



The DIII-D discharge shows an impressive set of parameters :  $\beta_N \approx 4$ , HHy2 $\approx 1.6$ , fB=0.75, at a qmin $\approx 2$  and q95=5, produced in a reversed shear q-profile, in presence of Internal Transport Barrier(ITB). Multiple feedback controls are needed to reach these achievements including resistive wall mode control using internal and external sets of magnetic coils, beta control using neutral beam injection and electron density control using gas-puffing. This dischange was run at low density and low radiation fraction.

The JT-60U discharge shown in fig.exhibits values HHy2=1.7, fB=0.92, ne/nG=0.87,  $b_N \approx 2.7$ realized in a reversed shear q-profile with formation of ITB. Although this discharge has achieved HHy2, fB and ne/nG reactor relevant the remaining issues are  $\beta_N$ , fuel purity, and radiation fraction.





### Pulsed DEMO design criteria



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### DEMO design



By specifying the aspect ratio, magnetic field, fusion power, temperature, density and fraction of Greenwald density, the size of the device and its plasma current is determined (the plasma current determined from n and Greenwald fraction, not from confinement requirements).

The H-factor is derived from power balance considerations rather than providing it as an input. In that way, a self-consistent solution to the simplified problem can be found.





### Determination of Ip, Bt



The plasma current is determined from the Greenwald density limit Line average nG=Ip/( $\pi a^2$ ) Since the neL=0.67npeak:

$$Ip(MA) = \frac{0.67}{0.8} \pi a^2 \frac{\hat{n}}{10^{20}} = 19.37 \frac{\delta = 0.45, A = 3.5}{\text{Ip} = 19MA}$$

$$B_T = \frac{q95}{5} \frac{A^2}{F_A S} Ip$$

we obtain:

 $\alpha 05 - 2 2 5 k - 1 75$ 

a B<sub>T</sub>=6.5T corresponding to q95=3.5

### **Relation Padd and H**



$$\left(\frac{Wth}{H_{IPBy2}f}10^{-6}\right)^{3.23} + \left(-P_{fus}/5 + (P_B + P_{syn} + P_{line-core})\right)/10^{6} = P_{AddHeat}(MW)$$

$$P\alpha - \left(P_B + P_{sync} + P_{line}\right) = \frac{2470}{5} - 363 = 131;$$

$$P_{AddHeat} \approx 5.2^{3.23} * H_{IPBy2}^{-3.23} - 131$$
For the plasma parameters considered
$$(T0=20 \text{keV}, n0=1 10^{20} \text{m}^{-3}, \text{BT}=6.5\text{T}, \text{Ip}=19\text{MA}, \text{fraction of Argon fAr}=nAr/ni=0.1\%, \text{and beryllium fraction fBe}=1\%), \text{the evaluation of the power loss appearing is:}$$

$$P_B \approx 165\text{MW}, P_{sync} \approx 6\text{MW}, P_{line-core} \approx \text{PBe} + \text{PAr}=2.4\text{MW} + 190\text{MW}; \text{Wth}=383\text{MJ}; \text{f}=220; \text{HIPBy2}=1}$$

$$P_{AddHeat} = 74\text{MW}$$



#### D3GW vs DEMO1 and PPCS A models



	O3G W	DEMO1 [13]	PPCS A[4]
R(m)	9,5	9	9,55
a(m)	2,7	2,25	3,18
А	3,5	4	3
В	6.5	7,1	7
Ip	19	16	30,5
n20			2,3(1.
(fG/Greenwald)	1(0.8)	1.2(1.)	2)
PH(MW)	74	50	246
Q	34	17	20
HHIPBy2	1	1	1,2
Pfus (GW)	2,5	1,9	5

The parameters of the O3GW device differ substantially in the ASPECT RATIO and density with respect to DEMO1 device

The PPCS A exhibit similar geom parameters to O3GW. The pulse length of O3GW could be compatible with tpulse= 6h ( see ref H Zohm) .

#### Demo1 CALCULATED BY PROCESS SYSTEM CODE



# Steady State vs pulsed



	SS	PULSED
PRO	SMALL RO	RELIABILITY
		SOLID BASIC
	SMALL IP	PLASMA SCENARIO
	LOW ASPECT RATIO	
	POSSIBLE	HIGH ASPECT RATIO
CONS	LARGE HCD	High COST
		CYCLIC FATIGUE ON
	SCENARIO TO BE	MAGNETS AND
	DEMONSTRATED	SUPERCONDUCTING
	EXTENSIVELY	COILS
	R&d NEEDED TO	PLASMA SCENARIO
	MAKE EFFICIENT CD	STILL TO BE
	SYSTEMS	COMPLETED
	CONTROLS AND	TO BE
	DIAGNOSE OF	CONTROLLED:
	CURRENT and	divertor and
CONTROLS	pressure profiles	radiation
	MHD CONTROLS:	
	RWM,NTMs	ELM and NTM



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#### Some advantages and issues for pulsed DEMO

The advantages of pulsed DEMO are residing in the fact that we know how to run the H-mode in plasmas where the current is largely inductive. The H-mode is a well established scenario,

#### however:

- there are large uncertainties in the power threshold needed for the access to the H-mode;
- ii) the possibility to run plasmas at a density higher than Greenwald density must be validated ;
- iii) the tools to mitigate the ELMs must be still fully developed;
- iv) The studies of cyclic operations on the machine components inducing creep/fatigue effects on vacuum vessel blanket modules etc are still in the initial phase.



Comparison of Dimensions of PPFC DEMO models with ITER : Pulsed (A/B) and Steady State C/D



Comparison between JET/ITER and DEMO



### **DEMO : DEMO-NSTRATION Device**

#### **DEMO SPECIFIC**

1. Due to TBR >1 the space available for diagnostics is likely < 5m<sup>2</sup>

2.Radiation :  $P_{rad}(P_{Br}+P_{Syn}+P_{linecore}) / (P_{alpha}+P_{Heating}) \sim 75\%$ 

3.Wall material /Divertor : metal Tungsten ( ITER: Be/W)

4.Neutron fluence : 30-50 X ITER Fluence

5. P<sub>alpha</sub>/P<sub>heating</sub>:

Device	ITER (Q=10)	DEMO1	DEMO2	ITER SS	SLIM CS	PPCS C
Palpha/Pheating	2	7,16	2,42	1	5,9	6,1
Palpha(MW)	100	358	500	72	590	682
Pheating(MW)	50	50	206	70	100	112
Pfus(GW)	0,5	1,8	2,5	0,36	2,95	3,41
Q	10	36	12	5	29,5	30





### **DIAGNOSTICS and CONTROLS for DEMO**

#### References : F P Orsitto et al IAEA FEC 2014 St Petersburg paper p7-8

**Conference Diagnostics for Fusion Reactors , Varenna september** 2013

F P Orsitto et al - EFDA TA DAS04- DEMO Instrumentation and Control –Final Report (july 2014)



### MAIN MESSAGES



•DEMO diagnostics should focus on high priority parameters: diagnostics for machine protection and basic control to be useful for BURN control in long pulses.

 The space available for diagnostics is severely limited by the TBR(Tritium Breeding Ratio) : a minimum set of systems is used to protect and control the machine.

The engineering of diagnostics must be inserted in the overall design of DEMO from the Beginning due to the optimization of the space dedicated, compatible with the TBR: **likely the organization of diagnostics in PORT PLUGS of ITER will NOT be used**.

- The high fluence of DEMO (30-50 x ITER fluence) put the other important constraint on the diagnostics: in practice the ITER diagnostics MUST BE REVISITED BECAUSE OF THE HIGH DPA IMPLIED IN DEMO OPERATIONS.
- Diagnostics (nearly) feasible (low extrapolation from ITER design and R&D needed)
   Microwave ( and Far Infrared Light ) techniques
   Direct line-of-sight techniques (neutrons, x-rays)

Strategy for diagnostics/control optimization



 ITER-like phase : assessment of control of Q>>10 scenario and control/training of prediction codes;

- BURN CONTROL in conditions where P<sub>alpha</sub>/P<sub>input</sub> ~7 is UNIQUE to DEMO
- The *training* of transport/prediction codes for Control will imply the use of diagnostics set similar to ITER

II) Power-plant phase : TBR >1.1 constraint , severely limits the access and minimum set of diagnostics must be used + codes





Environmental conditions more extreme than in ITER (>100 times higher neutron fluence):

No electrical and refractive components close to the plasma Limited application for first mirrors

Very limited access possibilities

Large emphasis on

Reliability, Maintainability, Robustness

Needs:

Development programme for new materials Testing under DEMO conditions



**T** Donne

### **ITER-LIKE** phase experience



In the ITER-LIKE phase two classes of outputs are **EQUALLY** important :

FIRST CLASS : Plasma operation quantities to guarantee the SAFE and optimal operation 1.Control of the burning Q>>10 phase ( for the pulsed device including ramp-up, flat top and ramp down )

- 2.the divertor power loads and detachment
- 3. disruption avoidance and mitigation

4.The simulation and control codes

SECOND CLASS: subsystems monitoring and safety

The diagnostics of the subsystems of the device include :

- i) Blanket modules
- ii) Heating systems
- iii) Wall erosion and damage monitoring
- iv) Dust measurements
- v) Creep-fatigue monitoring (pulsed DEMO)





#### Comparison of Surface Occupation (TBR $\geq$ 1.1)



Areas (m²)				
Machine	Diagnostics	Heating and Current Drive		
JET	10	3 + ICH antennae (internal)		
ITER	36	26 (includes HNB3 and LH)		
DEMO	3-5	6-10		





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#### **NEUTRON DAMAGE on DEMO1**









From the neutronics calculation :

Approx the level of damage calculated for ITER lifetime (i.e. 3dpa) Is found in DEMO at 0.5m from the First Wall in 5 full power years .

The First Mirror planned for ITER resistent to 3dpa can be used in DEMO At a deistance of 0.5m from the Vacuum Vessel .



Consequences of neutronics calculation on FM position



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### Short review of FM work so far

At moment Molibdenum(Mo) and Tungsten(W) mirror are considered as FM in ITER Results for Polarimetry/intefrometry using wavelengths  $\lambda \ge 100 \mu m$ 



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#### ) EUROfusion Example of Poloidal profile of neutron wall loading



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In the vertical ports the neutron flux is close to be 50% LESS than the equatorial OUTBOARD ports



### **Classification of diagnostics for DEMO**



- machine protection
- Basic control
- ADVANCED CONTROL (ITER-like phase)

machine protection	basic control	advanced control (*)
		alpha part
disruption	equilibrium	measurements
heat loads	burn control ( Te control)	current profile
		kinetic profiles
alpha losses	MHD control/CD control	( pedestal)
density control	ELM mitigation	
plasma position	Radiation control	
fusion power	kinetic measurements	
radiation profiles	divertor control	
magnetics equilibrium	Burn control (fuel and fuel	
(MHD markers)	ratio control)	

#### (\*)Not working in power plant phase





#### **Diagnostic systems FOR MACHINE PROTECTION**

Minimum set of dia for Machine protection(R&D needed) :

Magnetics (Hall sensors to be tested at high dpa>3, Low Temperature Co-fired Ceramic (LTCC)technology under test for ITER??)

IR Cameras (W or Mo mirrors to be tested for dpa>3)

Polarimetry (W or Mo mirrors to be tested for dpa>3)

Position reflectometry (ITER reflectometry nearly OK)

Fission chambers(ITER fission chambers to be qualified )

X-ray spectroscopy (X-ray mirrors and/or policapillary lenses to be tested)

VUV and Vis spectroscopy (\*)( W or Mo mirrors to be tested )

R Felton

(\*) using monitors of W emission close to 5nm , containing the quasi-continuum emission W 27+ - W 35+ and spectral lines at 0.794nm emitted by W 46+



### Magnetics



For ITER levels of exposure, parasitics are already dominated by sensor effects. Electronics for 12h pulses are demonstrated, but in-vessel sensors, although they could survive, have excessive drift

#### DEMO R&D should concentrate on robust and driftresistant sensor packages

## Placement of the sensors is extremely important: need locations with good poloidal flux penetration.

For parasitics at the level of the ITER sensors, DEMO will definitely need steady-state measurements to compensate for drifts, ideally in-vessel

Most promising technology is metallic Hall probes . For shape control, ITER may also well prove plasma position reflectometry is adequate, but this will require dedicated space allocation

Cabling is as important as the sensors: similar effects and harder to de G Vayakis maintain

### HALL sensor example

**EURO***fusion* 



**I DURAN** 



- Success in using Gen 2 DBC technology also for bismuth sensing layers.
- No problem with noise (up to ~150 degC) noise level about the same as for Cu while, signal is ~2000 times higher.
- Significant loss of sensitivity with rising temperature quadratic dependence.



### Neutronics







#### **POloidal POLArimetry**



Error of  $\Delta \theta$ : 0.1 degree<sup>4</sup> Error of  $\Delta \varepsilon$ : 0.6 degree<sup>4</sup>



Faraday Rotation Measurement Is Promising<br/>method in Future Reactor Due to High Resistance to<br/>Mirror DegradationImazawa

ITER :Measurements of Density (error 8%) and Temperature(error 30%) possible by polarimetry





#### In-Line ECE: Integration of ECE system in ECCD Transmission Line. Notch around gyrotron frequency

MHD CONTROL

- Co-located system
- Two implementations
  - TEXTOR (Quasi Optical)
  - AUG (CW, waveguides)
- Good news for DEMO
  - Plasma equilibrium not needed for NTM suppression









### **BURN CONTROL**



$$P_{\alpha} \approx C_{\alpha} f_{MIX} (nT)^{2} V$$

$$P_{alpha} = C_{\alpha} \langle ne^{2} \rangle \overline{\sigma v} E_{\alpha} V \gamma (1-\gamma)$$

$$\gamma = \frac{n_{T}}{n_{D} + n_{T}}$$

$$C_{\alpha} = dilution \ factor = (1 - 2f_{He} - Z_{Ar} fAr - Z_{Be} fBe)^{2} \ (ITER)$$

$$P_{loss} (W/m^{3}) \approx \frac{nT}{\tau E} \approx n^{1.91} * T^{3.26}$$

$$P_{RAD} \approx P_{Brem} \approx Zeff \ n^{2} T^{1/2}$$
To control
$$f_{MIX} \ and$$

 $\tau EIPBy2 \approx n^{-0.91} * T^{-2.26}$ 

Close to ignition

for 
$$P_{\alpha} \approx Ploss \Rightarrow C_{\alpha} (nT)^2 \approx n^{1.91} * T^{3.26} \Rightarrow$$
  
 $T \approx C_{\alpha} {}^{0.8} n^{0.07} f_{MIX} {}^{0.8}$   
 $P_{fusion} \approx 5 * C_{\alpha} {}^{2.6} n^{2.14} f_{MIX} {}^{2.6}$ 

In general BURN CONTROL is : Density Control Impurity Control Temperature Control ISOTOPIC MIX CONTROL

To control the Teq the sensible parameters are:  $f_{\rm MIX}$  and  ${\rm C}_{\alpha}.$ 

To control the burn the sensible parameters are : ne,  $f_{\text{MIX}}$  and  $\text{C}_{\alpha}.$ 

A tolerance of 10% in Pfus implies the possibility of changing  $\frac{\delta ne}{ne} \approx 5\%, \text{ and } \frac{\delta f_{MIX}}{f_{MIX}} \approx 4\%$ 

⇒ the accuracy needed for measurement of density is 1-2%⇒ the accuracy needed for measurement of fMIX is 1%. ⇒ A tolerance of 10% in the burn temperature implies the capability of changingthef<sub>MIX</sub> and dilution C<sub>a</sub> by 12.5% EUROfusion

#### **Diagnostics for Burn Control**



tecnical	diagnostics	BURN		
specifications	for	CONTROL		
		space	time	
	accuracy	resolution	resol	systems
Te (bulk)	5%	a/10	<100ms	ECE (Polarimetry)
				polarimetry ,
ne	1%	a/10	<100ms	reflectometry
				VUV-Xray
impurities	10%	integral	<100ms	spectr????
Zeff(line int.)	<20%	integral	<100ms	vis spectr ????
Pfus	10%	integral	<100ms	neutronics
confined fast				
ions	20%	a/10	100ms	NPA
nD/nT	10%	a/10	<100ms	NPA
core He				
density(nHe/ne)	10%	a/10	100ms	??
Ti(bulk)	10%	a/10	100ms	neutronics

Minimum set of Dia **BURN CONTROL:** ECE **Magnetics** Reflectometry **Polarimetry Neutronics VUV** spectroscopy Vis spectroscopy **NPA** 

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#### Readiness level of neutron diagnostics for DEMO



TRL 1	Basic principles observed and reported.
TRL 2	Technology concept and/or application
	formulated.
TRL 3	Analytical and experimental critical function
	and/or characteristic proof-of-concept.
TRL 4	Technology basic validation in a laboratory
	environment.
TRL 5	Technology basic validation in a relevant
	environment.
TRL 6	Technology model or prototype
	demonstration in a relevant environment.
TRL 7	Technology prototype demonstration in an
	operational environment.
TRL 8	Actual Technology completed and qualified
	through test and demonstration.
TRL 9	Actual Technology qualified through
	successful mission operations.





System	Likely detector	TRL (after ITER)	Justification
Neutron flux monitor system	Fission chambers	7	Used extensively on JET and other tokamaks, planned for ITER, main question is DT calibration accuracy
Neutron camera	Scintillator s, TOF	6 (7)	Used on JET,MAST etc, planned for ITER,
system			Near the plasma the system is mostly passive i.e. limited mechanical parts
			Number of lines of sight and detector choice are crucial to maximise number of measurable parameters and accuracy of results



### Planning of R&D for Diagnostics



The planning of R&D must take into account that

- a programme including the selection of tests of minimum set of sensors and control schemes must be carried out on ITER, JT-60SA and other devices available before DEMO comes into operation
- the use of codes like TRANSP or/and METIS for DEMO control can be started in the context Of ITM(International Tokamak Modelling) activity

### Demo DIA MACRO-AREAS



- 1. Burn control : DIAGNOSTICS FOR ALPHA PARTICLES , PLAMA TEMPERATURE, FUEL MIX
- 2.TRANSPORT CODES AND SINTHETIC DIAGNOSTICS : AN example is METIS CODE
- 3.Radiation hardening of diagnostics to be used continuously During the Power-plant-like phase



#### **R&D AND NEW CONCEPTS**



R&D NEEDS in DIAG	new concepts of diagnostics TO
Technology	BE DEVELOPED
magnetic sensors	LOST FAST PARTICLES
mirrors /schutters	
/cleaning techniques	MAGNETICS
	CURRENT PROFILE ( DIFFERENT
bolometers	FROM POLARIMETRY )
	SPECTROSCOPY :X-RAY , VIS
X-ray sensors	SPECTROSCPY
IR cameras	confined fast particles





### Tests on JET



1. Diagnostics for fast ( alpha ) particles

2.Neutron absolute calibration methods

3.Neutron and gamma spectroscopy : new diamond ( or SiC) detectors for neutron spectroscopy

4.Low and High energy Neutral Particle Analyzer( JET High-Energy NPA measures the energy distribution function of neutral H, D, T, 3He and 4He in the energy range 0.3 – 4 MeV.)

5.Neutron absorbers for gamma ray spectroscopy







- Fault detection
  - Detect sudden deviation of measurement from model prediction

**F** Felici

Isolate fault and exclude from reconstruction



### Conclusions



The elaboration of DEMO device parameters and concrete implementation Is now one of the objectives of fusion community

The DEMO models are now moving in the direction of a long pulse (3-4hours ) device With main inductive current

R0=9m BT=6.5T lp=17MA A=R0/a=3.6

Diagnostic systems need to be used for the control of burn and machine protection only

String R&D is starting : key point is resistence of the components to the high Neutron Fluence

Minimal set of diagnostics for DEMO control includes : IR systems (reflectometry, polarimetry) Neutronics (neutron /gamma cameras)

R&D needed in Mo and tungsten mirrors Development of control codes based on physics models

